

# Sydney Katz

Co-founder and CTO – Valgo

I am co-founder and CTO of Valgo (Valgorithmic, Inc.), a company focused on building safety validation tooling to support autonomous systems development and certification. I have deep expertise in algorithmic safety validation through my doctoral and postdoctoral research in the Stanford Intelligent Systems Laboratory. I also wrote a textbook called Algorithms for Validation and teach a related course at Stanford.

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## EDUCATION

### 🏛️ Stanford University

Aeronautics and Astronautics, MS/PhD

📅 2018 – 2023 📍 Stanford, CA

- **GPA:** 4.14 / 4.0
- **Thesis:** Safe Machine Learning-Based Perception via Closed-Loop Analysis

### 🏛️ Washington University in St. Louis

Electrical and Systems Engineering, BS/BSAS

📅 2014 – 2018 📍 St. Louis, MO

- **GPA:** 4.0 / 4.0
- **Valedictorian**

## RESEARCH EXPERIENCE

### Stanford Intelligent Systems Laboratory

📅 Researcher 📅 Fall 2018-Fall 2025 📍 Stanford, CA

**Keywords:** *safety-critical machine learning, perception, autonomy, validation, verification*

#### Postdoctoral Research

- Researching methods related to the **design and validation of safety-critical automated decision-making systems**
- **Algorithms for Validation:** authoring a textbook on algorithms for validating the performance of safety-critical decision-making systems using topics from optimization, probability theory, and formal methods [<online version>](#)
- **Mechanistic Interpretability:** exploring the ability to scale a traditional dictionary learning algorithm to disentangle high-dimensional embeddings from transformer models such as LLMs [<paper>](#) [<code>](#)
- **Uncertainty Quantification:** developing new techniques to quantify uncertainty in the pose estimation process for a vision-based landing system [<paper>](#) [<code>](#)
- **Mentoring** Master's and PhD students to set research goals, develop new ideas, and manage industry partnerships

#### Graduate Research

- **Perception System Safety Requirements:** developed efficient approach for determining safety requirements for perception systems [<paper>](#) [<video>](#) [<code>](#)
- **Safe Design of Perception Systems:** designed safer perception systems using a risk-driven approach that accounts for closed-loop safety properties [<paper>](#) [<video>](#) [<code>](#)
- **Verified Neural Network Perception:** created a method to formally verify image-based neural network controllers that uses generative models to capture the set of plausible inputs [<paper>](#) [<video>](#) [<code>](#)
- **Probabilistic Safety Guarantees for Neural Networks:** developed a technique to analyze the safety of neural network controllers used in stochastic environments [<paper>](#) [<video>](#) [<code>](#)
- **Preference-Based Learning:** used to develop a principled approach to generating realistic models from expert knowledge when data is scarce [<paper>](#) [<code>](#)
- **ACAS Xr:** extended ACAS X framework to apply to UAM vehicles by developing airspace models and new collision avoidance logic in initial concept study [<paper>](#) [<code>](#)

### Water Out Of Thin Air (WOOTA)

📅 Chief Technology Officer 📅 Fall 2014-Fall 2017 📍 St. Louis, MO

**Keywords:** *student-run, startup, design team*

- Designed a device that turns humidity into potable drinking water for people in developing countries
- Won the Washington University **Engineering Discovery Competition**, receiving \$25,000 for further development
- Iterated through three functioning prototypes while optimizing the efficiency of the design

### Aqueous Geochemistry and Mineralogy Group

📅 Undergraduate Student Researcher 📅 Fall 2014-Spring 2016 📍 St. Louis, MO

**Keywords:** *remote sensing, Mars, clay synthesis*

- Synthesized clays to create a reference dataset of spectral standards for Mars orbiters and rovers
- Analyzed results to determine implications for both remote sensing and in situ mineralogy

## WORK EXPERIENCE

### Valgo

🏢 Co-founder and CTO 📅 Fall 2025-present 📍 San Mateo, CA

**Keywords:** *safety validation, autonomy, risk estimation*

- Building tooling for algorithmic safety validation

### Reliable Robotics

🏢 GNC Intern 📅 Summer 2022 📍 Mountain View, CA

**Keywords:** *aircraft automation, machine learning, safety-critical system*

- Led implementation and analysis of **machine learning techniques** to support development of automated cargo aircraft
- Designed data collection procedures and set up model training and validation pipeline in Pytorch

### MIT Lincoln Laboratory

🏢 Research Intern 📅 Summer 2017/2018 📍 Boston, MA

**Keywords:** *aircraft collision avoidance, Markov decision process (MDP), safety-critical system, C++, Matlab*

- Supported testing of **Airborne Collision Avoidance System X (ACAS X)**
- Improved safety and decreased reversals in advisories for aircraft coordinating horizontal collision avoidance maneuvers by modifying **Markov decision process (MDP)** formulation
- Developed heuristic collision avoidance logic to test interoperability of ACAS X with other collision avoidance systems
- Integrated logic into C++/Matlab model for ACAS X simulations

### Infoscitex, a DCS Company

🏢 Operations Analyst Intern 📅 Spring 2017 📍 St. Louis, MO

**Keywords:** *sensor models, mission-level simulation*

- Worked with Advanced Framework for Simulation, Integration, and Modeling (AFSIM) performing mission level analysis applicable to the United States Air Force
- Developed sensor models for Advanced Air-to-Air Combat (A3C) simulations

### Johns Hopkins University Applied Physics Laboratory

🏢 NASA Intern 📅 Summer 2016 📍 Laurel, MD

**Keywords:** *GNC, satellite, Parker solar probe*

- Assisted with guidance and control for **NASA's Parker Solar Probe** mission (now in orbit around the sun)
- Enhanced solar illumination model for solar array control system analysis
- **Identified critical control system parameter change** to better manage arrays during momentum dumps

### NASA Glenn Research Center

🏢 Summer Intern 📅 Summer 2013-2015 📍 Cleveland, OH

**Keywords:** *design team, spacecraft concepts, trajectory optimization*

- Worked on the Collaborative Modeling for Parametric Assessment of Space Systems (COMPASS) design team to perform rapid integrated vehicle systems analyses
- Formulated and solved **trajectory optimization** problems for capturing a spacecraft into the Neptune/Triton system
- Updated the COMPASS database to allow customers and team members to understand trends in payload mass, dry mass, cost, power, etc., specifically in Solar Electric Propulsion (SEP) vehicles
- Developed **high temperature materials** (composites and aerogels) for use in both spacecraft and aircraft (2013)

## LEADERSHIP AND TEACHING

### Validation of Safety-Critical Systems

🏢 Stanford University 📅 Winter 2025 📍 Stanford, CA

- Instructor for a new course that covers algorithms that can be used to ensure the safe operation of decision-making systems used in high-stakes settings
- Developed course materials such as lecture slides, programming assignments, and exercises
- Lecture videos are [publicly available online](#)

### Teaching Assistant

🏢 Stanford University 📍 Stanford, CA

- **Designing Robust and Reliable AI Systems** (Summer 2023): Assisted with the development and execution of a week-long course with the Stanford Center for Professional Development
- **Decision Making Under Uncertainty** (Winter 2023): class of over 450 students, managed programming assignments, held weekly office hours
- **Engineering Design Optimization** (Spring 2021): managed programming assignments, held weekly office hours, and gave lecture on gradient-based optimization
- **Building Trust in Autonomy** (Winter 2021): designed assignments and curriculum for undergraduate seminar

## AI4ALL Mentor

🏛 Stanford University 📅 Summer 2021/2023 📍 Stanford, CA

- **Led the robotics group and developed curriculum** for a three-week summer camp to introduce high school students from underrepresented backgrounds to AI concepts and topics

## Outreach Videos

🏛 Stanford University 📍 Stanford, CA

- **Stanford Intelligent Systems Laboratory:** producer for a documentary detailing the first ten years of the lab
- **Neural Network Verification:** created an introductory video on neural network verification
- **Markov Chain Monte Carlo:** intuitive explanation of Markov chain Monte Carlo in 10 minutes

## Residential Peer Mentor

🏛 Washington University in St. Louis 📅 Fall 2015 - Spring 2018 📍 St. Louis, MO

- Served as a resource for **150 calculus and physics students**, holding 6 office hours per week
- Conducted formal review sessions attended by 50-100 students before each major exam

## Langsdorf Scholars Summit Co-Chair

🏛 Washington University in St. Louis 📅 Fall 2017 - Spring 2018 📍 St. Louis, MO

- Proposed and executed idea to invite over 450 Langsdorf Scholar alumni back to Washington University campus for a weekend reunion and networking event
- Served as co-chair of the planning committee

## Engineering Tutor and Course Grader

🏛 Washington University in St. Louis 📅 Fall 2017 - Spring 2018 📍 St. Louis, MO

- Tutored individually for Electronic Circuits, Introductory Physics, and Signals and Systems
- Graded weekly quizzes for Engineering Electromagnetic Principles

## Jump Rope Instructor

📅 Spring 2015 - Spring 2018 📍 St. Louis, MO

- Started jump rope club at local St. Louis elementary school to share my knowledge of the sport of competitive jump rope
- Expanded club to include over 30 participants

## FELLOWSHIPS

📅 2020-2023 **National Science Foundation Graduate Research Fellow**

*Three years of funding and support for graduate research*

📅 2018-2020 **Stanford Graduate Research Fellow**

*Initial funding and support during Master's degree*

📅 2014-2018 **Langsdorf Fellow**

*Full-tuition merit scholarship to attend Washington University in St. Louis*

📅 2014-2018 **McKelvey Research Scholar**

*Provided funds and support to perform undergraduate research at Washington University in St. Louis*

## HONORS AND AWARDS

📅 2025 **Stanford AIAA Excellence in Teaching Award**

*For outstanding contributions in teaching (selected by students)*

📅 2021 **Third Place in Student Research Competition**

*Digital Avionics Systems Conference (DASC)*

📅 2021 **Best Paper of Session**

*Digital Avionics Systems Conference (DASC)*

📅 2019 **Best Paper of Session**

*Digital Avionics Systems Conference (DASC)*

📅 2018 **Valedictorian**

*Washington University in St. Louis School of Engineering and Applied Science*

📅 2018 **David H. Levy Outstanding Senior Award**

*Washington University in St. Louis Department of Electrical and Systems Engineering*

📅 2017 **Russell R. Pfeiffer Outstanding Junior Award**

*Washington University in St. Louis Department of Electrical and Systems Engineering*

- 📅 2017 **Outstanding Junior Leader Award Nominee**  
Washington University in St. Louis
- 📅 2017 **Tau Beta Pi**  
Engineering Honor Society
- 📅 2017 **Infoscitex Star Award**  
For strong performance as an intern
- 📅 2016 **Antoinette Francis Dames Award for Productive Scholarship in Engineering**  
Washington University in St. Louis School of Engineering and Applied Science
- 📅 2016 **Outstanding Sophomore Award**  
Washington University in St. Louis Department of Electrical and Systems Engineering
- 📅 2016 **Outstanding Sophomore Leader Award Nominee**  
Washington University in St. Louis

## INVITED TALKS

- 📅 2025 **Offline POMDP Solutions**  
AA228 Decision Making Under Uncertainty Guest Lecture (Stanford, CA)
- 📅 2025 **AI Safety Webinar**  
Stanford Online (Virtual)
- 📅 2025 **How to Make Good Presentations**  
TRex Bio (South San Francisco, CA)
- 📅 2025 **How to Make Good Presentations**  
Stanford Online (Stanford, CA)
- 📅 2025 **Validation of Complex Decision-Making Systems**  
Horasis Visionary Circle (Stanford, CA)
- 📅 2025 **Verification and Validation of Safety-Critical Decision-Making Systems**  
University of Auckland Space Institute Seminar (Auckland, NZ)
- 📅 2025 **Building a Safety Case for AI in Aviation**  
IEEE International Conference on Robotics and Automation Workshop (Atlanta, GA)
- 📅 2025 **Multiobjective Optimization**  
AA222 Engineering Design Optimization Guest Lecture (Stanford, CA)
- 📅 2024 **Validation of AI Systems for Use in High-Stakes Settings**  
CS120 Guest Lecture (Stanford, CA)
- 📅 2024 **Validation of AI Systems for Use in High-Stakes Settings**  
Amazon Lab126 (Sunnyvale, CA)
- 📅 2024 **Safe Machine Learning-Based Perception and Open Problems in Scaling Formal Methods**  
Dagstuhl Seminar 24361 (Wadern, Germany)
- 📅 2024 **Algorithms for Validation**  
Dagstuhl Seminar 24361 (Wadern, Germany)
- 📅 2024 **Algorithms for Validation**  
Stanford Center for AI Safety Annual Meeting (Stanford, CA)
- 📅 2024 **Building a Safety Case for AI in Aviation**  
GenAI x Aerospace Hackathon (Hillsborough, CA)
- 📅 2023 **Safe Machine Learning-Based Perception via Closed-Loop Analysis**  
AIAA Air Traffic Systems Webinar (Virtual)
- 📅 2023 **Safe Machine Learning-Based Perception via Closed-Loop Analysis**  
Sandbox AQ (Palo Alto, CA)
- 📅 2023 **Efficient Determination of Safety Requirements for Perception Systems**  
Digital Avionics Systems Conference (Barcelona, Spain)
- 📅 2023 **Efficient Determination of Safety Requirements for Perception Systems**  
NASA ULI Safe Aviation Autonomy Monthly Seminar (Virtual)
- 📅 2023 **Safe Machine Learning-Based Perception via Closed-Loop Analysis**  
Airbus Acubed (Sunnyvale, CA)
- 📅 2022 **Verification and Validation of Safety-Critical Autonomous Systems**

- 📅 2022 **Verification and Validation of AI Systems**  
Reliable Robotics (Mountain View, CA)
- 📅 2022 **Operational Impact of Speed Change Advisories as Aircraft Collision Avoidance Maneuvers**  
AIAA Aviation Forum (Virtual)
- 📅 2022 **Verification and Validation of Safety-Critical Autonomous Systems**  
Trustworthy Autonomous Systems Governance Node (Edinburgh, Scotland)
- 📅 2021 **Generating Probabilistic Safety Guarantees for Neural Network Controllers**  
NASA ULI Safe Aviation Autonomy Monthly Seminar (Virtual)
- 📅 2021 **Verification of Image-Based Neural Network Controllers using Generative Models**  
Digital Avionics Systems Conference (San Antonio, TX)
- 📅 2019 **Learning an Urban Air Mobility Encounter Model from Expert Preferences**  
Digital Avionics Systems Conference (San Diego, CA)

## PUBLICATIONS

- Kochenderfer, M. J., **Katz, S. M.**, Corso, A. L., and Moss, R. J. *Algorithms for Validation*. MIT Press, 2026. URL: <https://algorithmsbook.com/validation/files/val.pdf>.
- Delecki, H., **Katz, S. M.**, and Kochenderfer, M. J. "Failure Probability Estimation for Black-Box Autonomous Systems using State-Dependent Importance Sampling Proposals". In: *International Conference on Control, Decision and Information Technologies (CODIT)*. 2025. URL: <https://arxiv.org/abs/2412.02154>.
- Valentin, R., **Katz, S. M.**, Vanhoucke, V., and Kochenderfer, M. J. "DB-KSVD: Scalable Alternating Optimization for Disentangling High-Dimensional Embedding Spaces". In: *ArXiv* 2505.18441 (2025). URL: <https://arxiv.org/abs/2505.18441>.
- Valentin, R., **Katz, S. M.**, Lee, J., Arief, M., Sorgenfrei, M., Walker, D., and Kochenderfer, M. J. "Uncertainty aware pose estimation and calibration from image features". In: *Digital Avionics Systems Conference (DASC)*. 2024.
- **Katz, S. M.** "Safe machine learning-based perception via closed-loop analysis". PhD thesis. Stanford University, 2023. URL: <https://searchworks.stanford.edu/view/14781481>.
- **Katz, S. M.**, Corso, A. L., Yel, E., and Kochenderfer, M. J. "Efficient determination of safety requirements for perception systems". In: *Digital Avionics Systems Conference (DASC)*. 2023. URL: <https://arxiv.org/pdf/2307.01371.pdf>.
- Rober, N., **Katz, S. M.**, Sidrane, C., Yel, E., Everett, M., Kochenderfer, M. J., and How, J. P. "Backward reachability analysis of neural feedback loops: Techniques for linear and nonlinear systems". In: *IEEE Open Journal of Control Systems* (2023), pp. 1–18. DOI: 10.1109/OJCSYS.2023.3265901.
- Smyers, E. Q., **Katz, S. M.**, Corso, A., and Kochenderfer, M. J. "AVOIDDS: Aircraft vision-based intruder detection dataset and simulator". In: *Advances in Neural Information Processing Systems (NeurIPS)*. 2023.
- Corso, A. L., **Katz, S. M.**, Innes, C. A., Du, X., Ramamoorthy, S., and Kochenderfer, M. J. "Risk-driven design of perception systems". In: *Advances in Neural Information Processing Systems (NeurIPS)*. 2022. URL: <https://arxiv.org/pdf/2205.10677.pdf>.
- **Katz, S. M.**, Alvarez, L. E., Owen, M., Wu, S., Brittain, M. W., Das, A., and Kochenderfer, M. J. "Collision risk and operational impact of speed change advisories as aircraft collision avoidance maneuvers". In: *AIAA AVIATION Forum*. 2022. DOI: 10.2514/6.2022-3824.
- **Katz, S. M.**, Corso, A. L., Strong, C. A., and Kochenderfer, M. J. "Verification of image-based neural network controllers using generative models". In: *Journal of Aerospace Information Systems* (2022). DOI: 10.2514/1.I011071. URL: <https://arxiv.org/abs/2105.07091>.
- Sidrane, C., **Katz, S. M.**, Corso, A. L., and Kochenderfer, M. J. "Verifying Inverse Model Neural Networks". In: *arXiv preprint arXiv:2202.02429* (2022). URL: <https://arxiv.org/abs/2202.02429>.
- Strong, C. A., **Katz, S. M.**, Corso, A. L., and Kochenderfer, M. J. "ZoPE: A fast optimizer for ReLU networks with low-dimensional inputs". In: *NASA Formal Methods Symposium (NFM)*. 2106.05325. 2022. URL: <https://arxiv.org/abs/2106.05325>.
- **Katz, S. M.**, Corso, A. L., Strong, C. A., and Kochenderfer, M. J. "Verification of image-based neural network controllers using generative models". In: *Digital Avionics Systems Conference (DASC)*. 2021. DOI: 10.1109/DASC52595.2021.9594360. URL: <https://arxiv.org/pdf/2105.07091.pdf>.
- **Katz, S. M.**, Julian, K. D., Strong, C. A., and Kochenderfer, M. J. "Generating probabilistic safety guarantees for neural network controllers". In: *Machine Learning* 2103.01203 (2021). DOI: 10.1007/s10994-021-06065-9. URL: <https://arxiv.org/abs/2103.01203>.
- **Katz, S. M.**, Maleki, A., Biyik, E., and Kochenderfer, M. J. "Preference-based learning of reward function features". In: *ArXiv* 2103.02727 (2021). URL: <https://arxiv.org/abs/2103.02727>.



- Weinert, A. J., Edwards, M., Alvarez, L., and **Katz, S. M.** “Representative Small UAS Trajectories for Encounter Modeling”. In: *AIAA Scitech 2020 Forum*. 2020, p. 0741.
- **Katz, S. M.**, LeBihan, A.-C., and Kochenderfer, M. J. “Learning an urban air mobility encounter model from expert preferences”. In: *Digital Avionics Systems Conference (DASC)*. 2019. doi: 10.1109/DASC43569.2019.9081648. URL: <https://arxiv.org/abs/1907.05575>.
- Casanova, S., Henry de Frahan, J., Guimaraes Goecks, V., Herath, S., Herreras Martinez, M., Jamieson, N., Jones, T., Kang, S. W., **Katz, S. M.**, Li, G., et al. “Enabling deep space exploration with an in-space propellant depot supplied from lunar ice”. In: *AIAA SPACE and Astronautics Forum and Exposition*. 2017, p. 5376.
- **Katz, S. M.**, Nickerson, R. D., Ehlmann, B. L., and Catalano, J. G. “Synthesis and Analysis of Synthetic Smectite Clays for Use as Spectral Standards”. In: *Lunar and Planetary Science Conference*. 1903. 2016, p. 1683.

## REVIEW ACTIVITIES

### Journals

*Journal of Artificial Intelligence Research*  
*Journal of Aerospace Information Systems*  
*IEEE Control Systems Letters*  
*Journal of Air Transportation*  
*Machine Learning Journal*  
*Engineering Applications of Artificial Intelligence*  
*IEEE Robotics and Automation Letters*  
*IEEE Transactions on Automatic Control*

### Conferences

*International Conference on Intelligent Robots and Systems (IROS)*  
*American Control Conference (ACC)*  
*Learning for Dynamics and Control (L4DC)*  
*International Conference on Automation Science and Engineering (CASE)*  
*Advanced in Neural Information Processing Systems (NeurIPS)*